

## Process Control And Dynamics Solution Manual

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Title Page: Preface: Symbols and Acronyms: Part I: Introduction: 1-2: 1: Introduction to Process  
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Thomas F. Edgar and Duncan A. Mellichamp. Variables :  $w_1, w_2, T_1, T_2, T_3$ .  $N_E = 1, N_V = 5$ . Thus,  $N_F = 5 - 1 = 4$ . Because  $w_1, w_2, T_1$  and  $T_2$  are determined by upstream units, we assume they are known functions of time:  $w_1 = w_1(t), w_2 = w_2(t)$

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Calendar Description: The dynamic behaviour and automatic control of processes are studied.

Mathematical tools for analyzing the transient behaviour of open and closed-loop systems are presented.

The steps of controller development are treated: process characterization (using mathematical models), controller design, and implementation.

CHEE319: Process Dynamics and Control

Solved: 1. Consider the second order model:  $4 \frac{d^2x(t)}{dt^2} + 8 \frac{dx(t)}{dt} + 4x(t) = 4u(t)$ , with  $x(t)$  as step. Using the solution for a second order lag subject to a step response from the

Answer: Process Dynamics and Control Questions

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